

10 Mar. 2021.

Last time:

- Recovery of individual sparse vecs.
→ $m \geq n$ is sufficient
- NP hardness of ℓ_0 min.
- ℓ_1 minimization.

Today:

- ℓ_1 min. → sparse solns.
- OMP algorithm.

Thm 3.1 Let $A \in \mathbb{R}^{m \times N}$ be a mesc. matrix with cols.

a_1, a_2, \dots, a_N . Assuming uniqueness of a minimizer $\underline{x^*}$ of (P_1) : $\min_{x \in \mathbb{R}^N} \|x\|_1$, s.t. $Ax = y$, the system $\{a_j, j \in \text{supp}(x^*)\}$ is LS, and $\|x^*\|_0 \leq m$.

Proof: Suppose $\{a_j, j \in S\}, S \subseteq \text{supp}(x^*)$ are LD.

Then, $\exists \alpha + \nu \in \mathbb{R}^N$, $\text{supp}(\alpha) \subseteq S$, s.t. $A\nu = 0$.

Then, for any $t \neq 0$,

$$\begin{aligned} \|x^* + t\nu\|_1 &< \underbrace{\|x^* + t\nu\|_1}_{\text{sub-optimal feasible pt.}} = \sum_{j \in S} |x_j^* + t\nu_j| \\ &= \sum_{j \in S} \text{sgn}(x_j^* + t\nu_j) (x_j^* + t\nu_j). \end{aligned}$$

For t small enough, $|t| < \min_{j \in S} \frac{|x_j^*|}{\|\nu\|_\infty}$

$$\text{sgn}(x_j^* + t\nu_j) = \text{sgn}(x_j^*), \forall j \in S.$$

$$\|x^* + t\nu\|_1 < \sum_{j \in S} \text{sgn}(x_j^*) (x_j^* + t\nu_j)$$

$$\begin{aligned} &= \sum_{j \in S} \text{sgn}(x_j^*) x_j^* + t \sum_{j \in S} \text{sgn}(x_j^*) \nu_j \\ &= \|x^*\|_1 + t \left(\sum_{j \in S} \text{sgn}(x_j^*) \nu_j \right) \end{aligned}$$

contradiction. ∵ can choose $t \neq 0$ s.t. the RHS is less than $\|x^*\|_1$. □Real valued case: (P_1) is a linear program.Slack variables $\bar{z}^1, \bar{z}^2 \in \mathbb{R}^N$:

$$z_j^1 = \begin{cases} z_j & \text{if } z_j \geq 0, \\ 0 & \text{if } z_j < 0, \end{cases} \quad z_j^2 = \begin{cases} 0 & \text{if } z_j \geq 0, \\ -z_j & \text{if } z_j < 0. \end{cases}$$

Then (P_1) can be written as

$$\min_{\bar{z}^1, \bar{z}^2 \in \mathbb{R}^N} \sum_{j=1}^N (z_j^1 + z_j^2) \quad \text{s.t.} \quad [A - I] \begin{bmatrix} \bar{z}^1 \\ \bar{z}^2 \end{bmatrix} = y$$

$$\begin{bmatrix} \bar{z}^1 \\ \bar{z}^2 \end{bmatrix} \geq 0.$$

Given the soln. $(\bar{z}^1)^*$, $(\bar{z}^2)^*$ of the above LP,the soln. to the pb. (P_1) is $x^* = (\bar{z}^1)^* - (\bar{z}^2)^*$.

Complex case:

$$\text{Approach 1: } \min_{z \in \mathbb{C}^N} \|z\|_0 \quad \text{s.t.} \quad Az = y.$$

$$\text{Write } \bar{z} = \begin{bmatrix} z_R \\ z_I \end{bmatrix} = \begin{bmatrix} u \\ v \end{bmatrix} \in \mathbb{R}^{2N}.$$

$$u = z_R = \text{Real}(z), \quad v = z_I = \text{Imag}(z) \in \mathbb{R}^N.$$

$$\text{Then solve } \min_{\bar{z} \in \mathbb{R}^{2N}} \|\bar{z}\|_1 \quad \text{s.t.} \quad \begin{bmatrix} \text{Real}(A) & -\text{Imag}(A) \\ \text{Imag}(A) & \text{Real}(A) \end{bmatrix} \bar{z} = \bar{y},$$

$$\text{where } \bar{y} = \begin{bmatrix} \text{Real}(y) \\ \text{Imag}(y) \end{bmatrix} \in \mathbb{R}^{2M}.$$

$$\text{Approach 2: [Quadratically constrained basis pursuit]} \quad \min_{z \in \mathbb{C}^N} \|z\|_1 \quad \text{s.t.} \quad \|Az - y\|_2 \leq \eta \quad (P_{1,2}).$$

$$\text{Introduce } c \in \mathbb{R}^N \quad \text{s.t.} \quad c_j \geq |z_j| = \sqrt{u_j^2 + v_j^2}, \quad j \in [N].$$

Then, $(P_{1,2})$ is equiv. to

$$\min_{c, u, v \in \mathbb{R}^N} \sum_{j=1}^N c_j \quad \text{s.t.} \quad \left\| \begin{bmatrix} \text{Real}(A) & -\text{Imag}(A) \\ \text{Imag}(A) & \text{Real}(A) \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} - \begin{bmatrix} \text{Real}(y) \\ \text{Imag}(y) \end{bmatrix} \right\|_2 \leq \eta$$

$$\sqrt{u_j^2 + v_j^2} \leq c_j, \quad j \in [N]$$

This is a second order cone program (SOCP).

Given its soln. (c^*, u^*, v^*) , the soln. to $(P_{1,2})$ is

$$x^* = u^* + i v^*.$$

Some related convex opt. problems:

$$1. \text{ Quadratically constrained basis pursuit: (QCBP)}$$

$$(BP_\eta): \min_{z \in \mathbb{C}^N} \|z\|_1 \quad \text{s.t.} \quad \|Az - y\|_2 \leq \eta.$$

2. Basic pursuit denoising (BPDN): For some $\lambda \geq 0$

$$\min_{z \in \mathbb{C}^N} \lambda \|z\|_1 + \|Az - y\|_2 \quad [\text{BPDN}]$$

3. LASSO: For some $\tau \geq 0$

$$\min_{z \in \mathbb{C}^N} \|Az - y\|_2 \quad \text{s.t.} \quad \|z\|_1 \leq \tau$$

4. Dantzig selector $\tau \geq 0$

$$\min_{z \in \mathbb{C}^N} \|z\|_1 \quad \text{s.t.} \quad \|A^T(Az - y)\|_\infty \leq \tau$$

$$\left(\max_{j \in [N]} |a_j^T (A z - y)| : \text{small} \right)$$

Prop. (a) If x is a minimizer of BPDN w/ $\lambda > 0$, then $\exists \eta = \eta_x > 0$ s.t. x is a minimizer of QCBP.(b) If x is a unique of QCBP, w/ $\eta \geq 0$.then $\exists \tau = \tau_x > 0$ s.t. x is a unique min. of Lasso.(c) If x is a min. of Lasso w/ $\tau > 0$,then $\exists \lambda = \lambda_x > 0$ s.t. x is a min. of BPDN.

3.2. Greedy Methods.

Orthogonal Matching Pursuit (OMP)

Assume cols of A have unit ℓ_2 norm. $y = \underline{AO}$ Init. $S^0 = \{\emptyset\}$, $x^{(0)} = 0$, $n=0$.

Repeat:

$$\underline{j_{n+1}} = \arg \max_{j \in [N]} \{ |(\underline{A}^H (\underline{y} - \underline{A}\underline{x}^{(n)}))_j| \}$$

$$S^{n+1} = S^n \cup \{j_{n+1}\}$$

$$\underline{x}^{(n+1)} = \arg \min_{z \in \mathbb{C}^N} \{ \|y - Az\|_2 \mid \text{supp}(z) \subseteq S^{n+1} \}$$

Until a stopping criterion is met.Output $\underline{x}^{(n+1)}$.

$$j_{n+1} \notin S^n \because \underline{A}_{S^k} \in \mathbb{C}^{m \times |S^k|}$$

$$\min \|A_{S^k} \underline{x}_{S^k} - y\|_2^2, \quad \underline{x}_{S^k} \in \mathbb{C}^{|S^k|}$$

$$\underline{A}_{S^k}^H (\underline{A}_{S^k} \underline{x}_{S^k} - y) = 0 \\ -r^k, \text{ the residual.}$$

$$\underline{A}_{S^k}^H r^k = 0.$$

 r^k orthogonal to the cols of A indexed by S^k . \Rightarrow if $j \notin S^k$, it will not be chosen

in the next iteration.